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(56) Documents cited

GB 2181250 A

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(54) Aircraft health and usage monitoring system

(57) An aircraft health and usage monitoring system comprises a computer system (D.A.P.U.) for processing data relating to both flight profiles and selected indicators of health and usage of an aircraft, supplied by sensors which monitor the flight profile and the selected indicators. The computer system has predetermined thresholds therein in respect of the selected indicators and is arranged to record the duration and extent by which any threshold is exceeded in use of the aircraft. The indicators of the health and usage of the aircraft are selected from the following: engine health, transmission health, airframe health, aircraft systems health.

The aircraft may be a helicopter.

FIG. 1. BHL INTEGRATED FLIGHT RECORDING, HEALTH AND USAGE MONITORING SYSTEM (IHUNS)

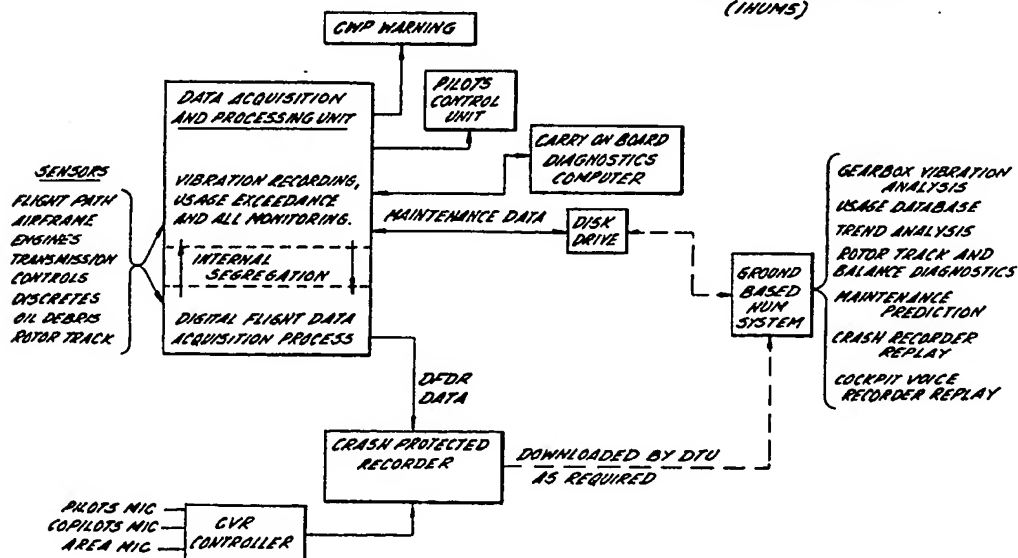
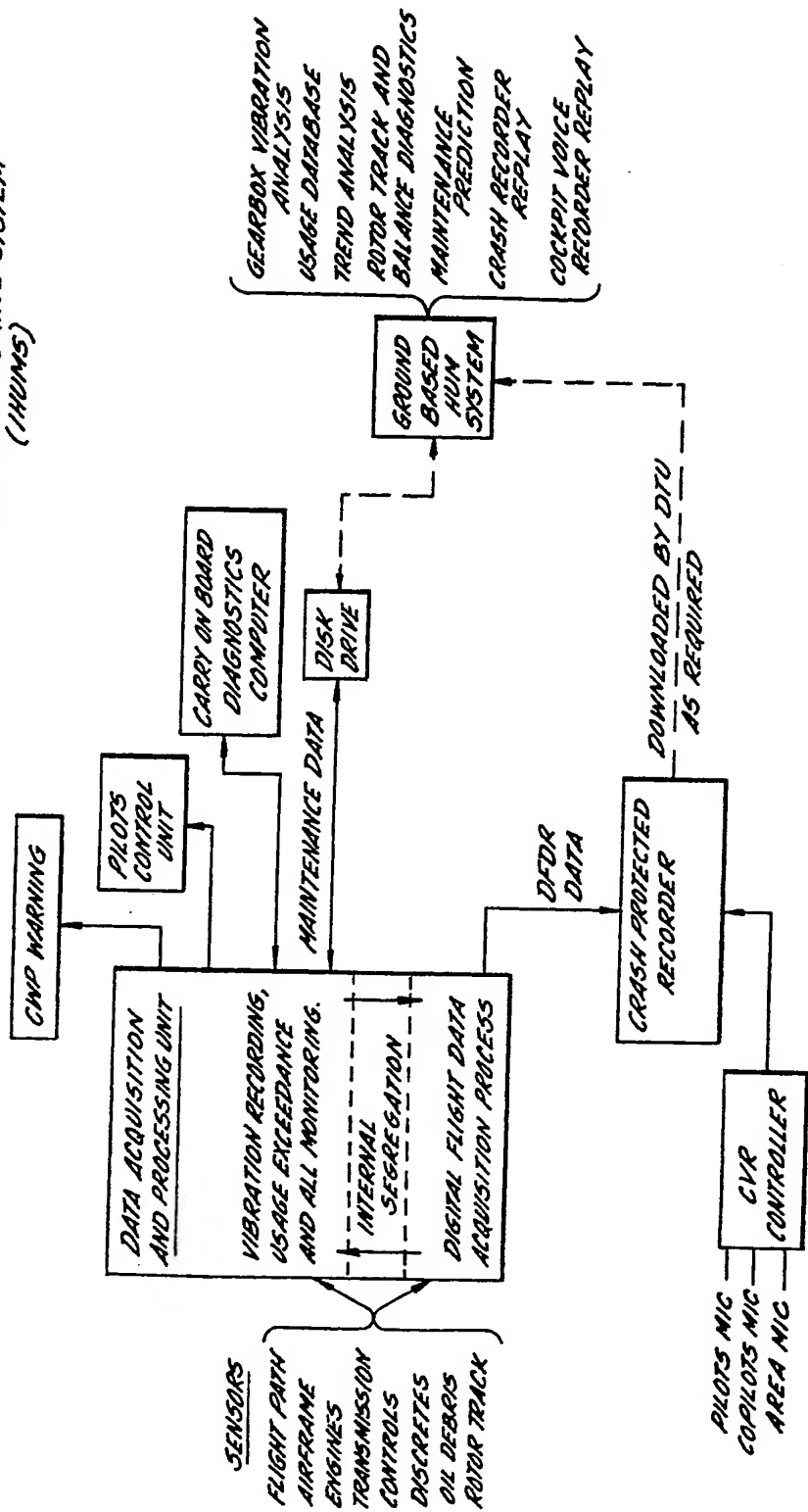
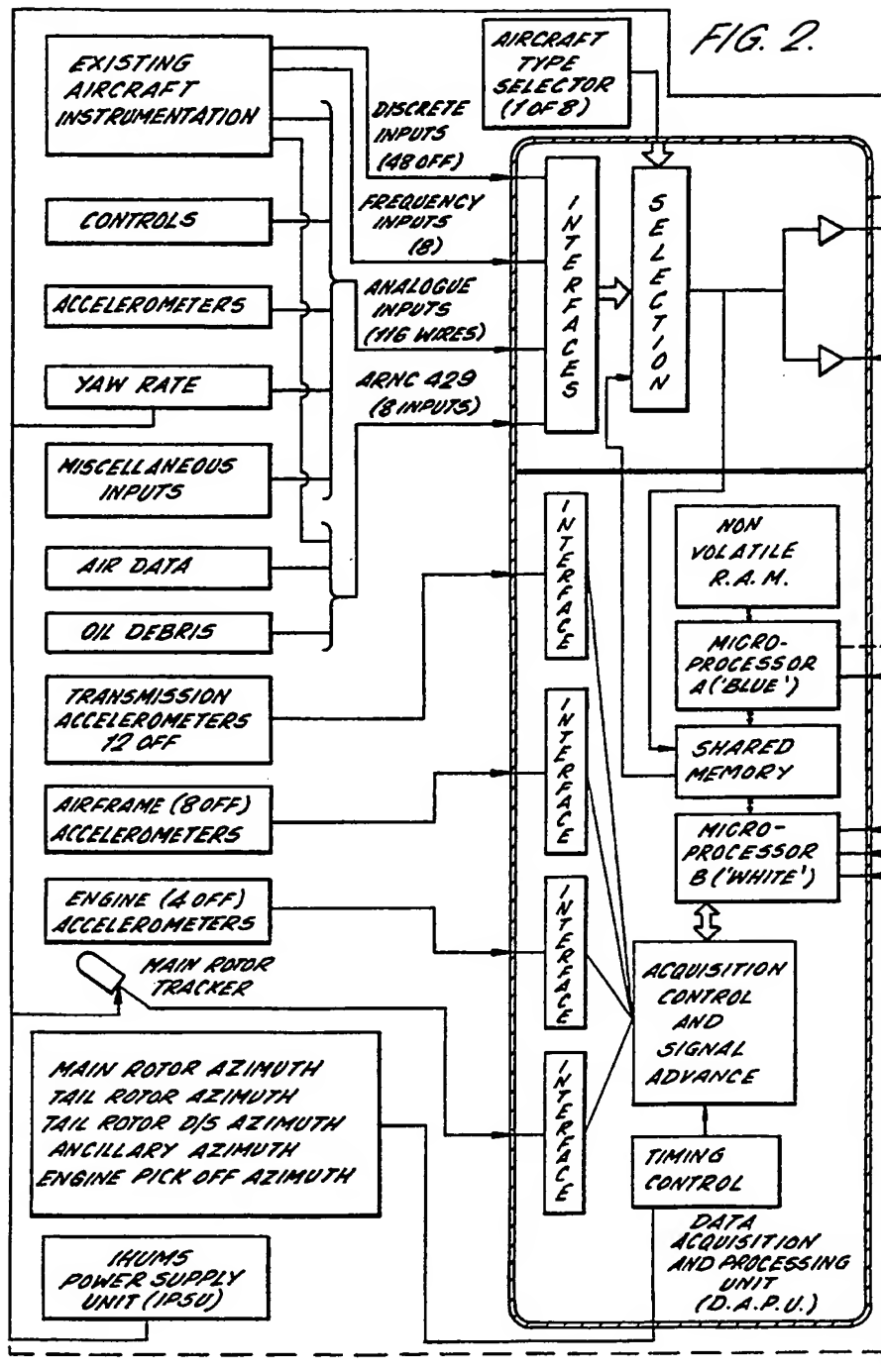


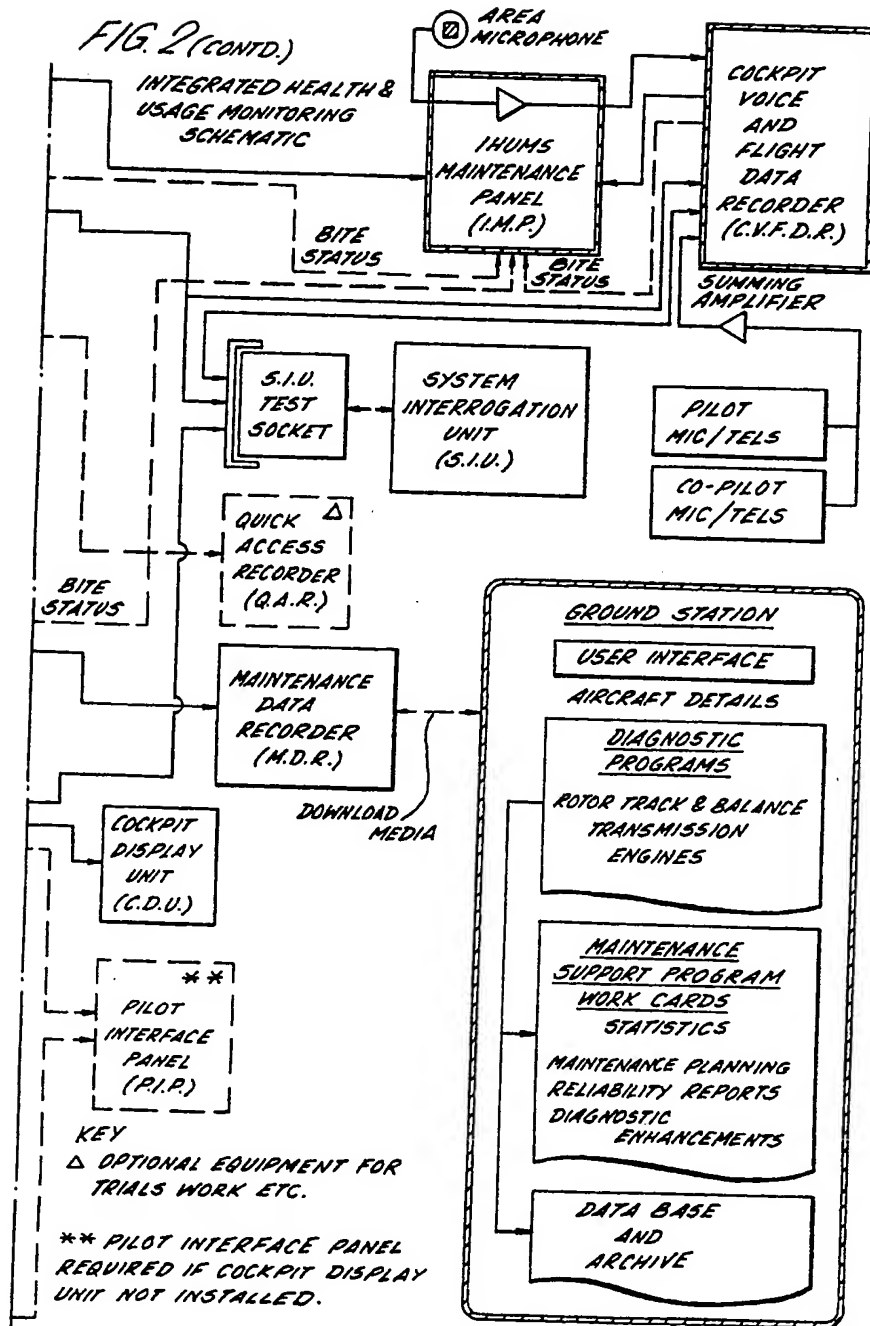
FIG. 1. BHL INTEGRATED FLIGHT RECORDING, HEALTH AND USAGE MONITORING SYSTEM (IHUMS)



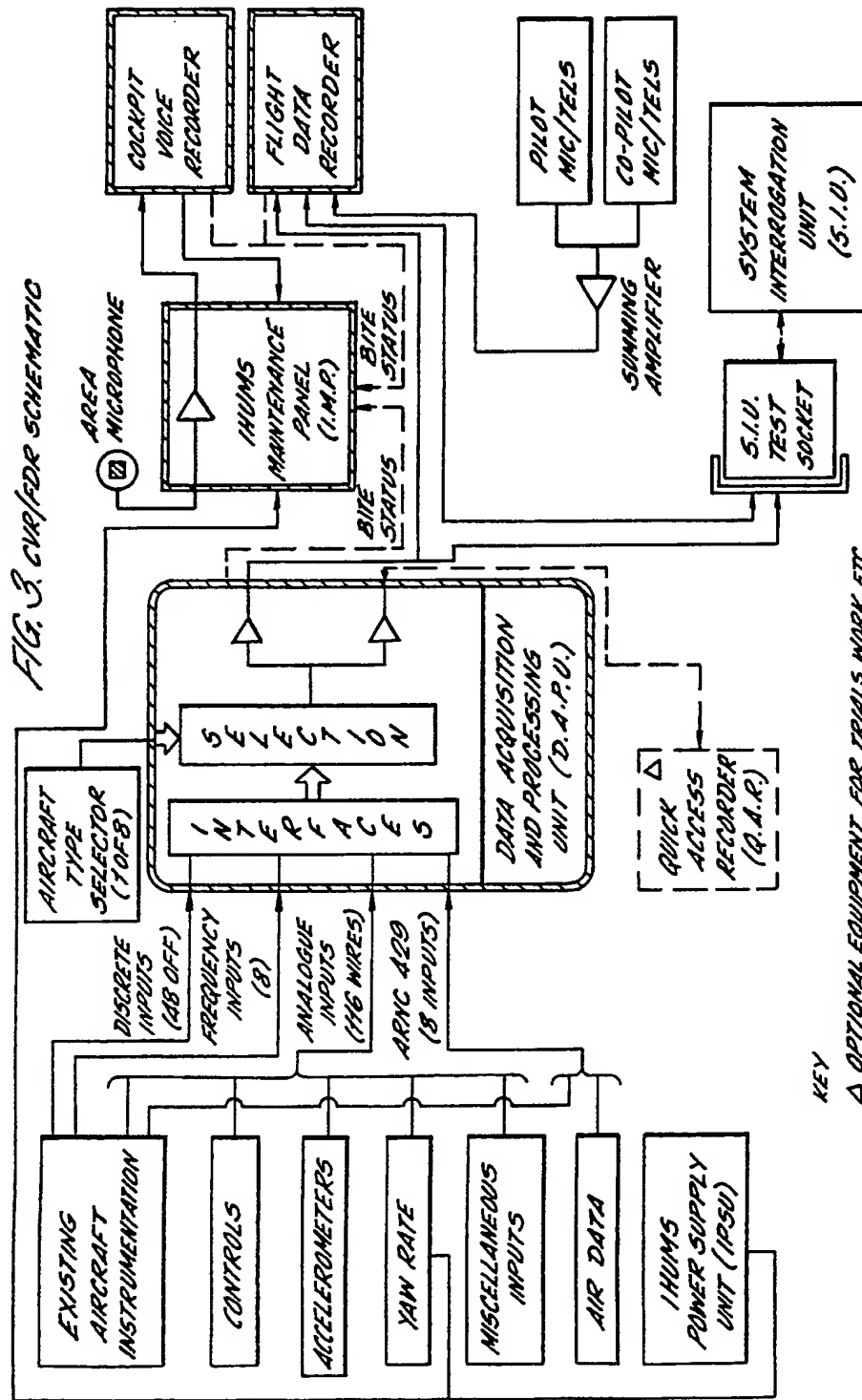
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FIG. 4.

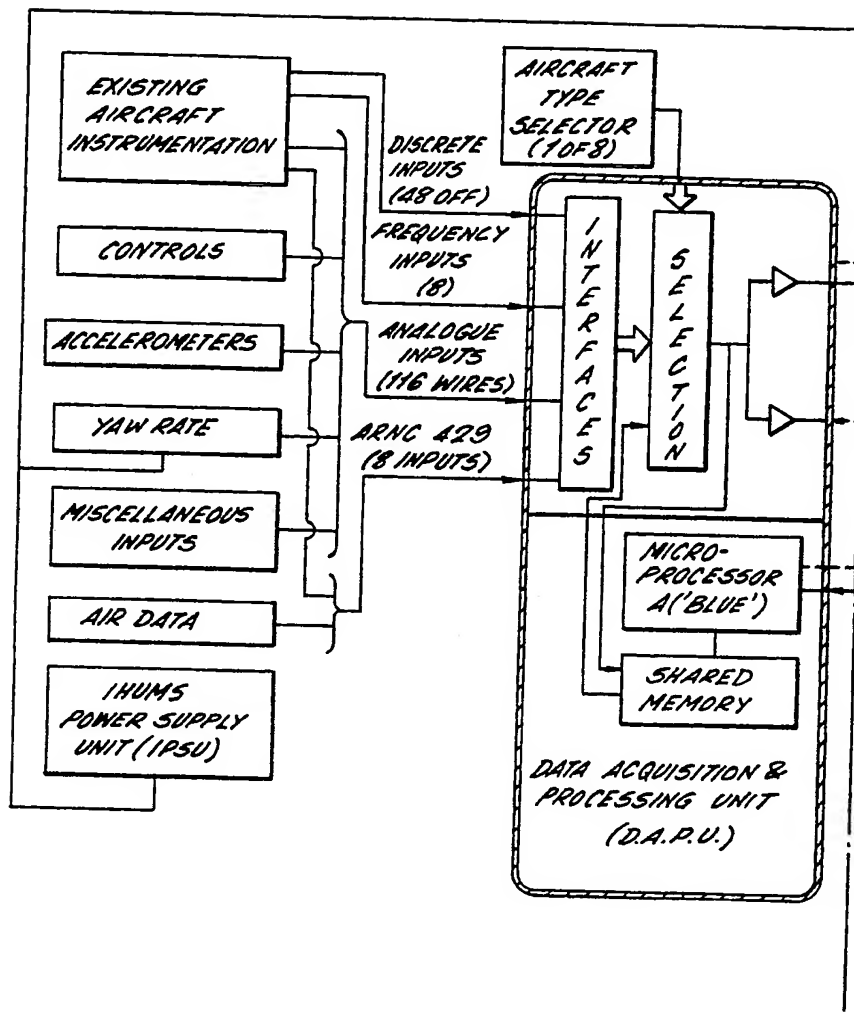
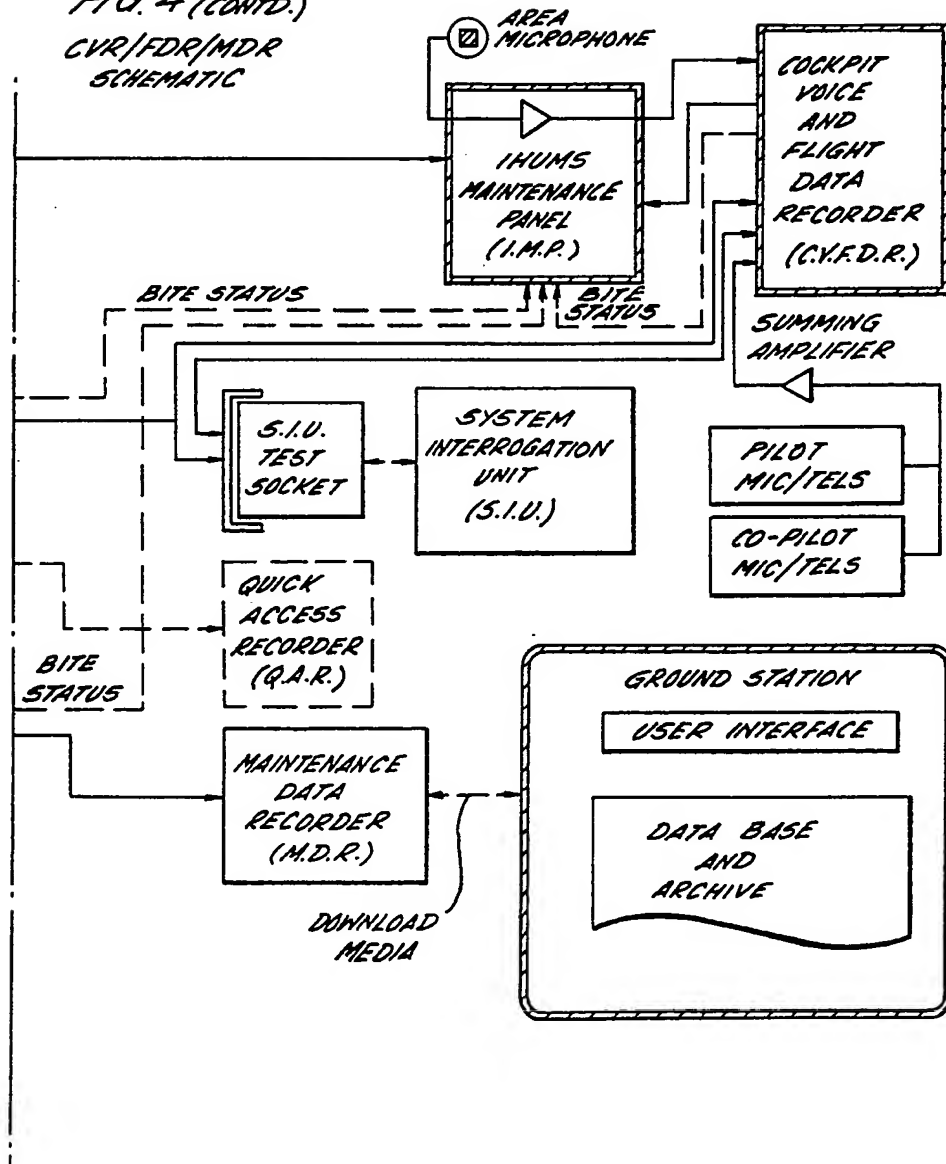
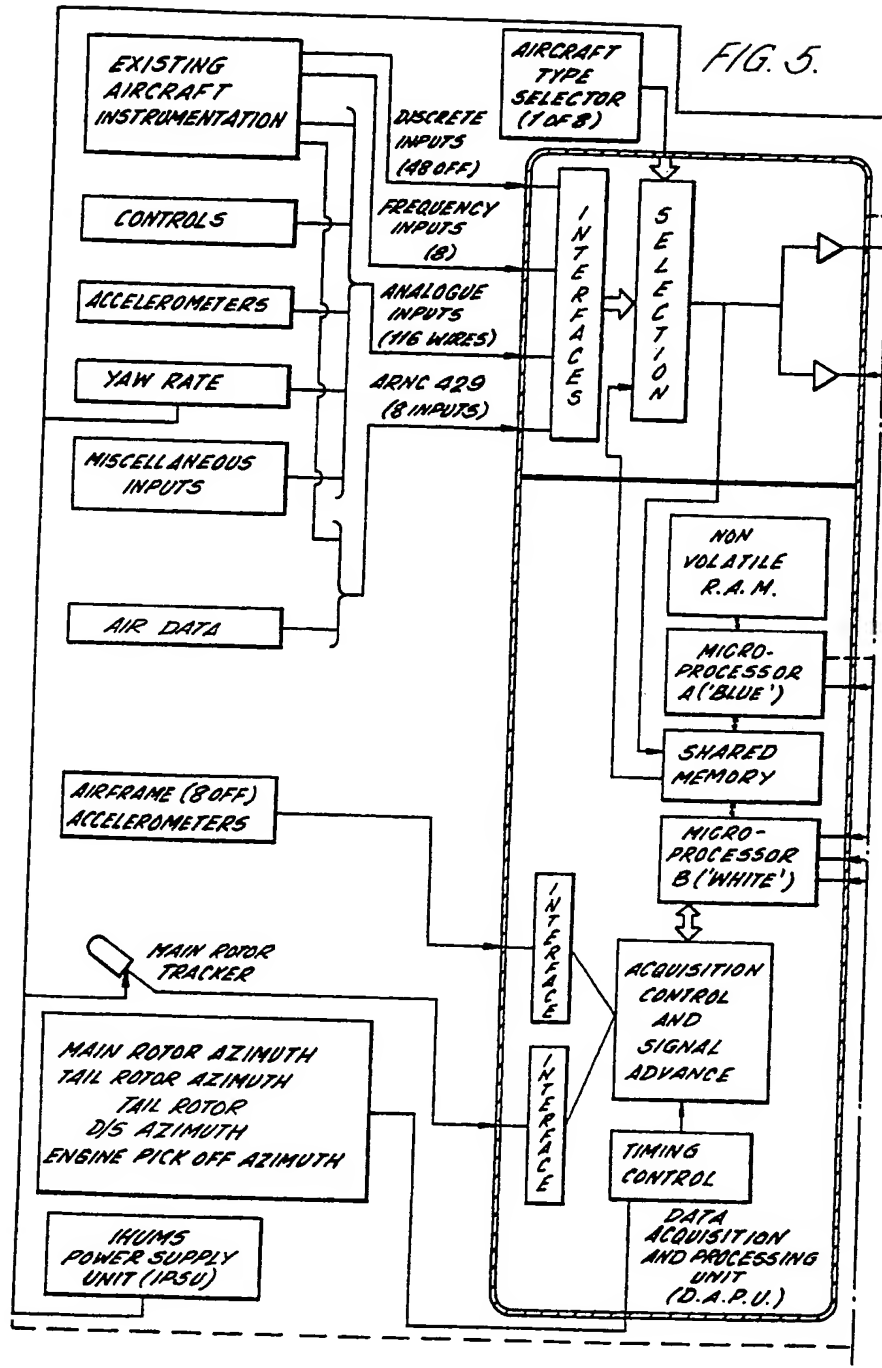


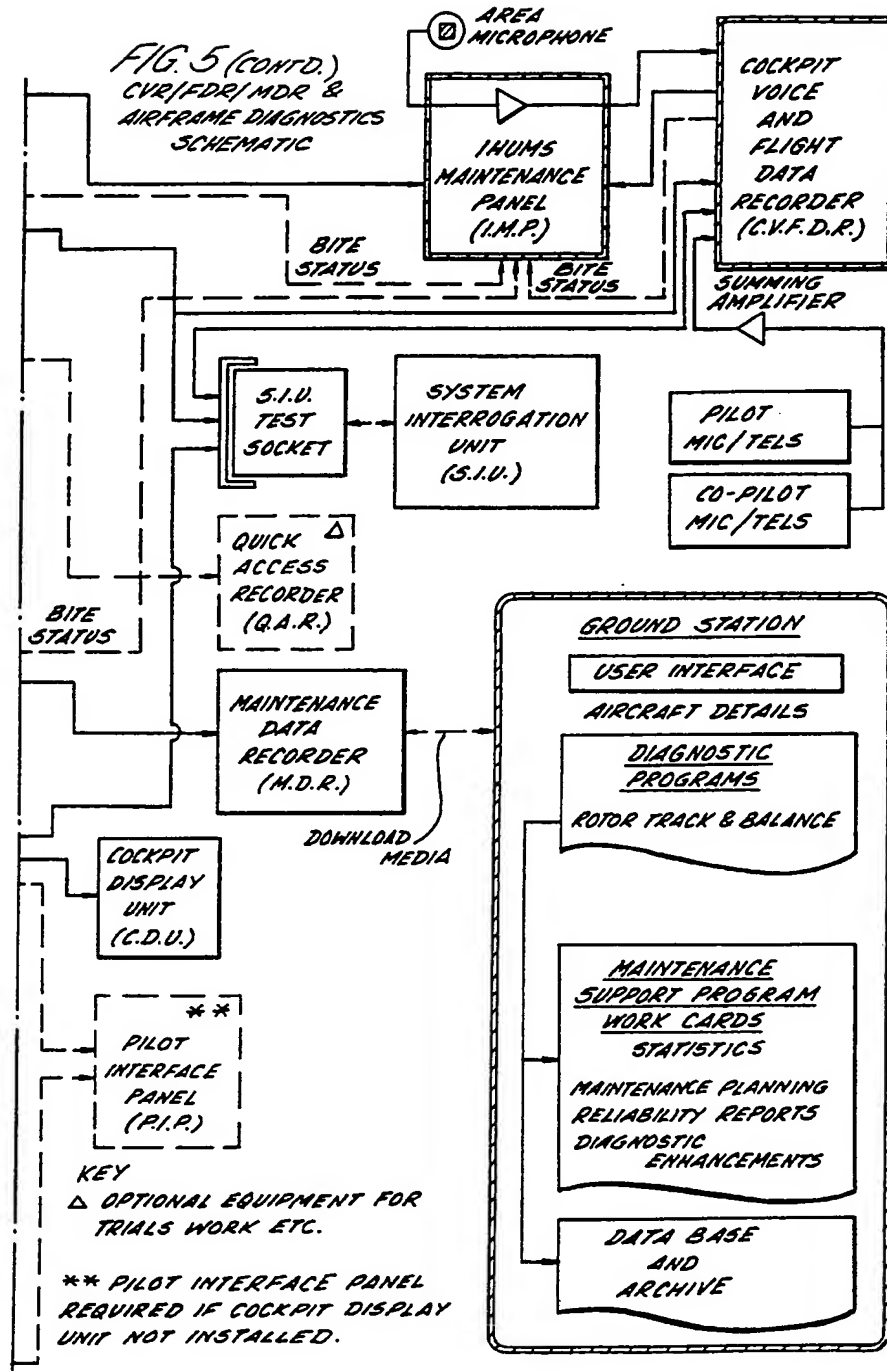
FIG. 4 (CONTD.)
CVR/FDR/MDR
SCHEMATIC



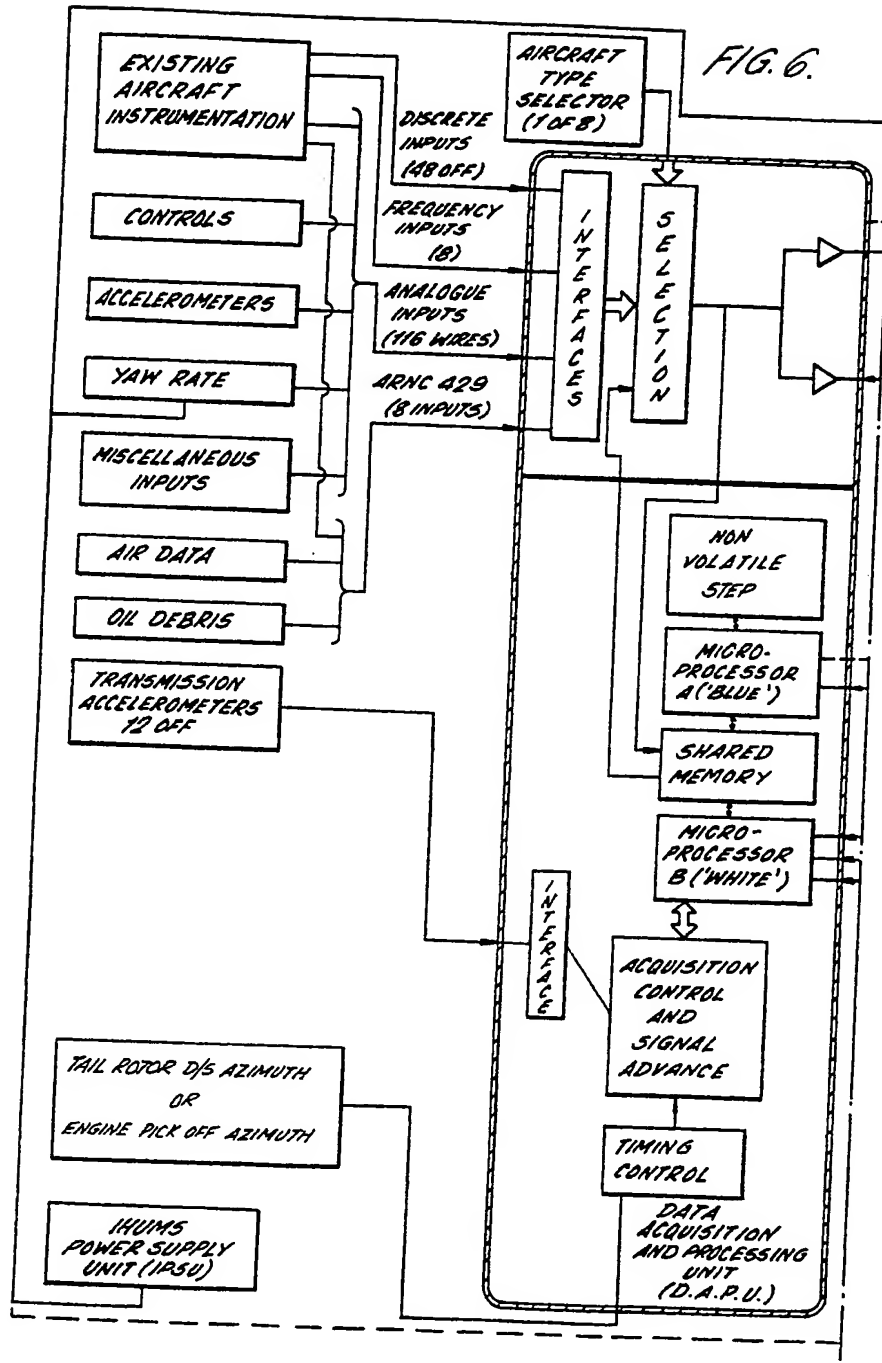
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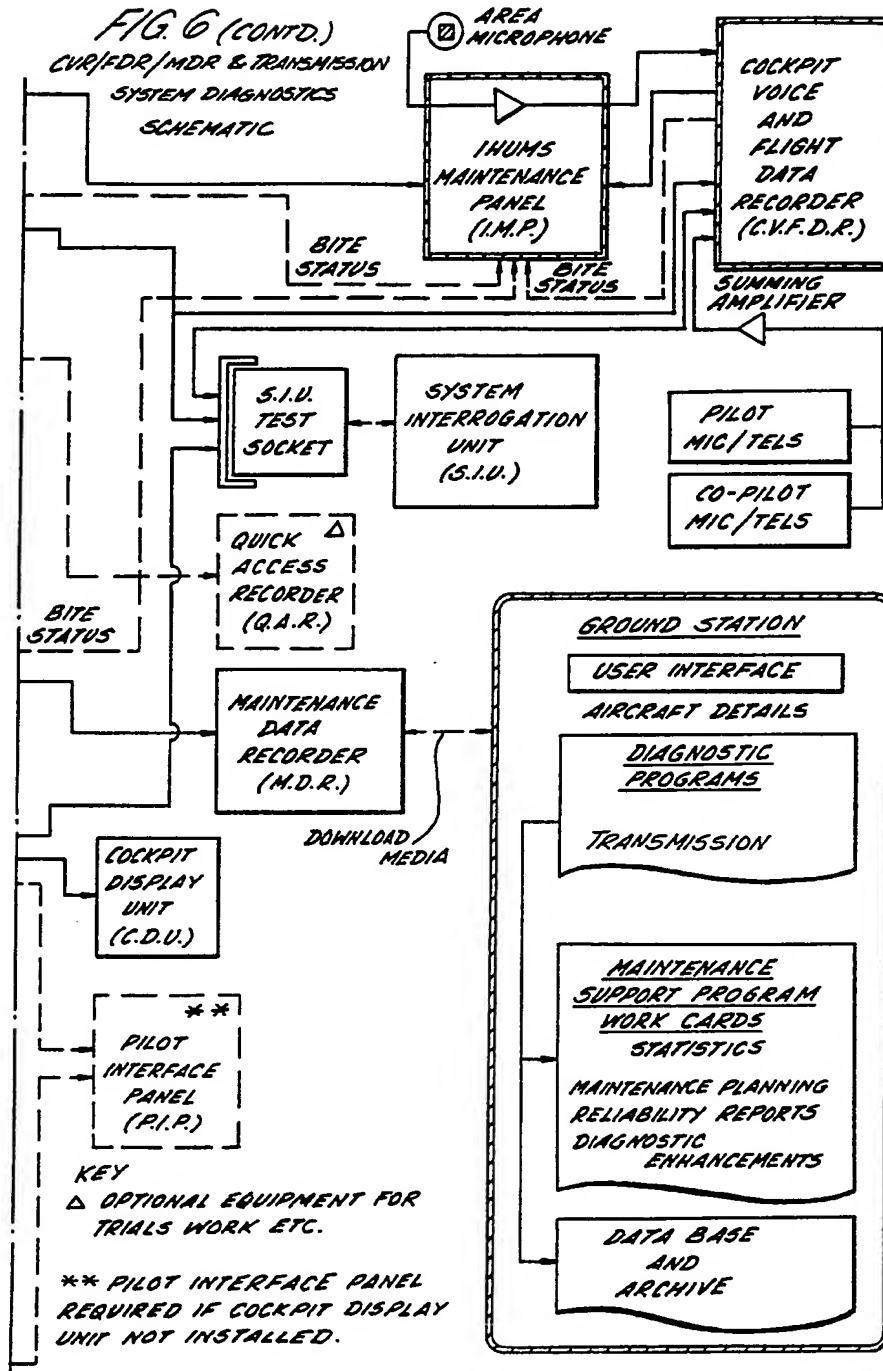
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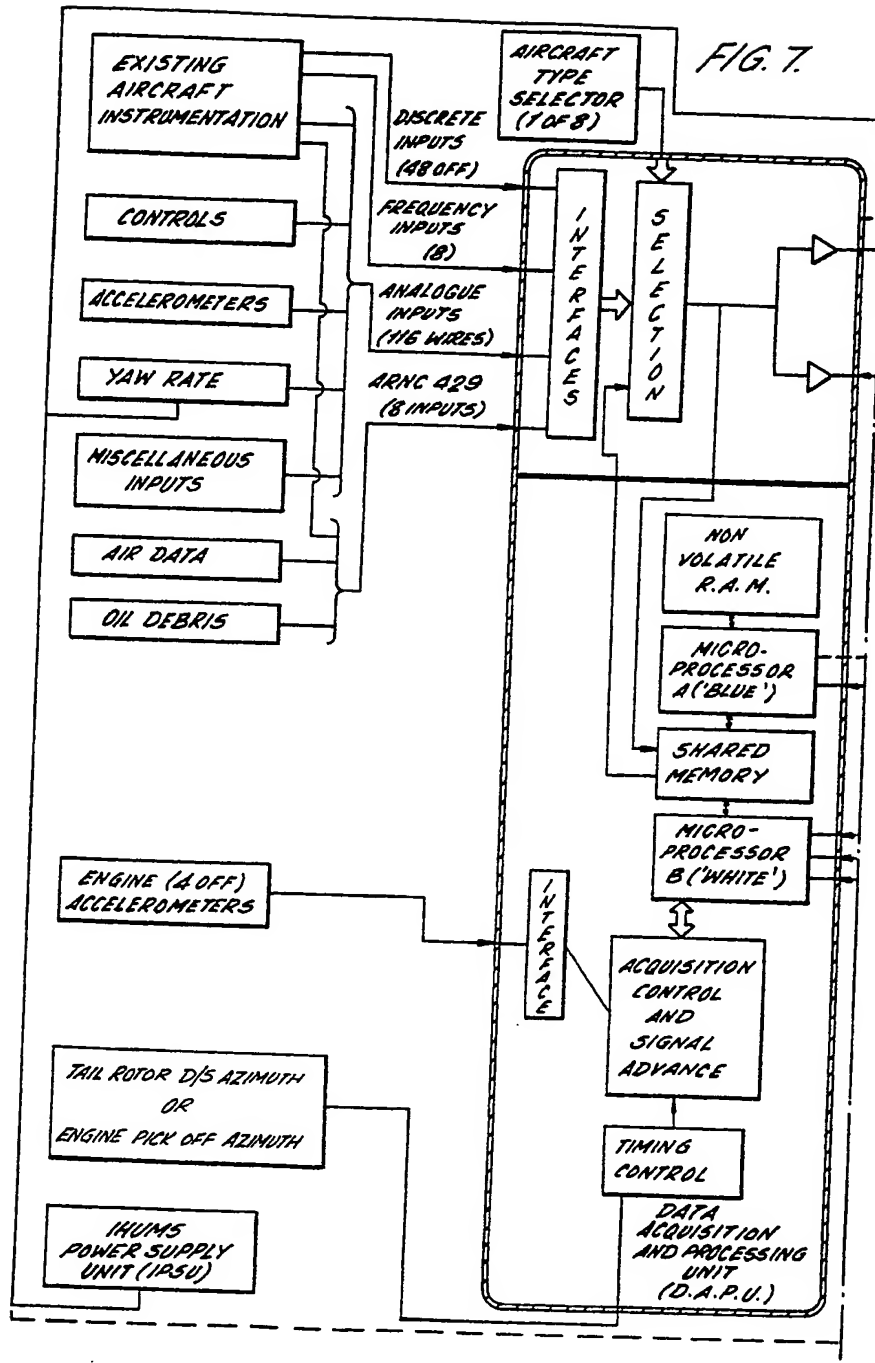
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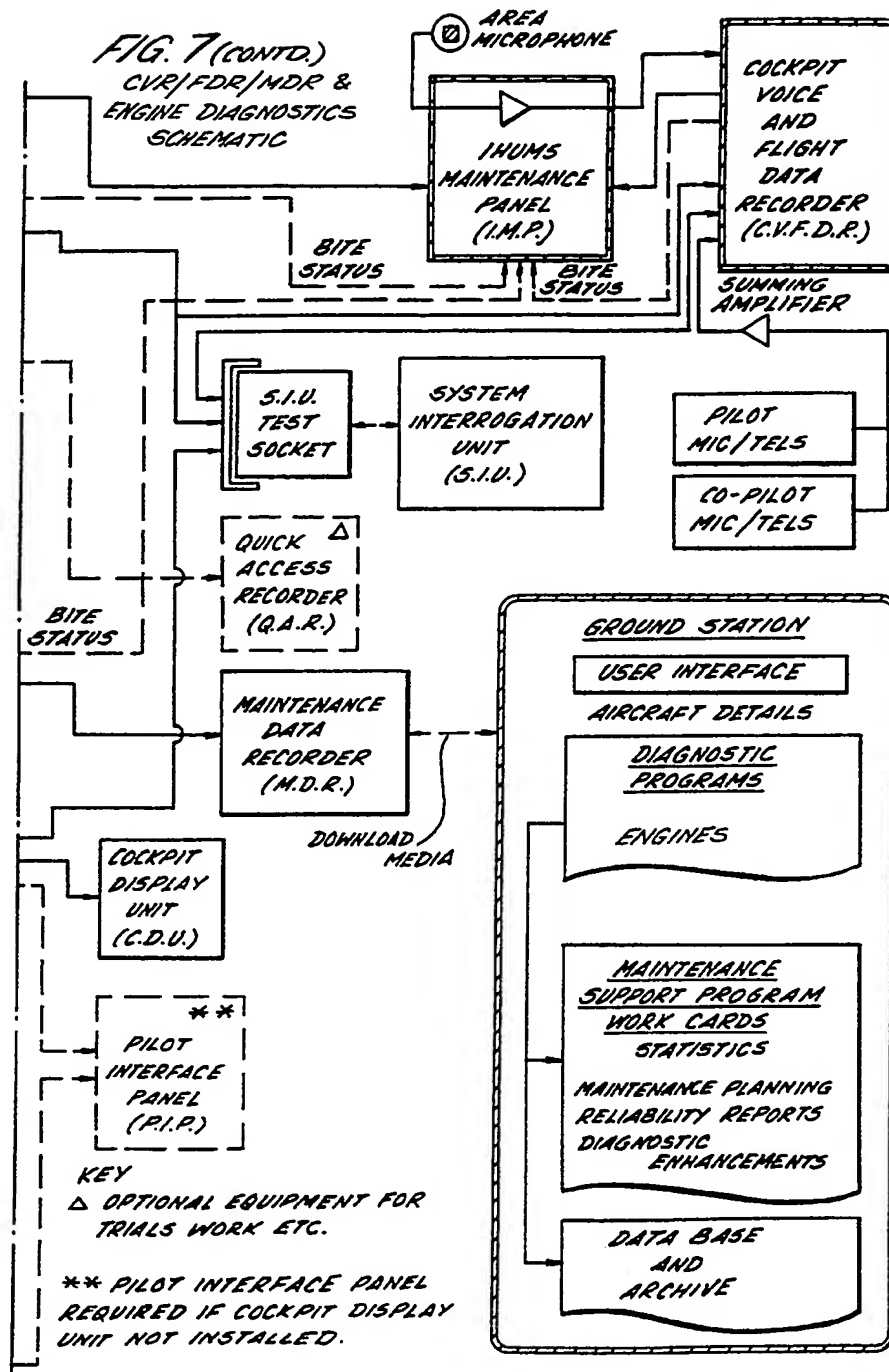
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FIG. 8.

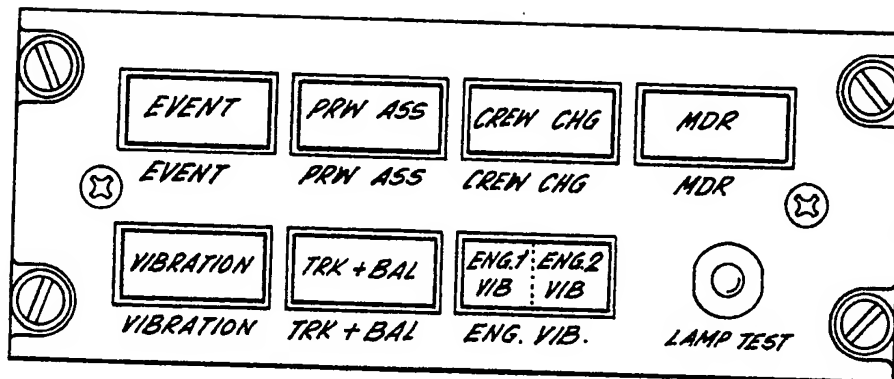


FIG. 9.

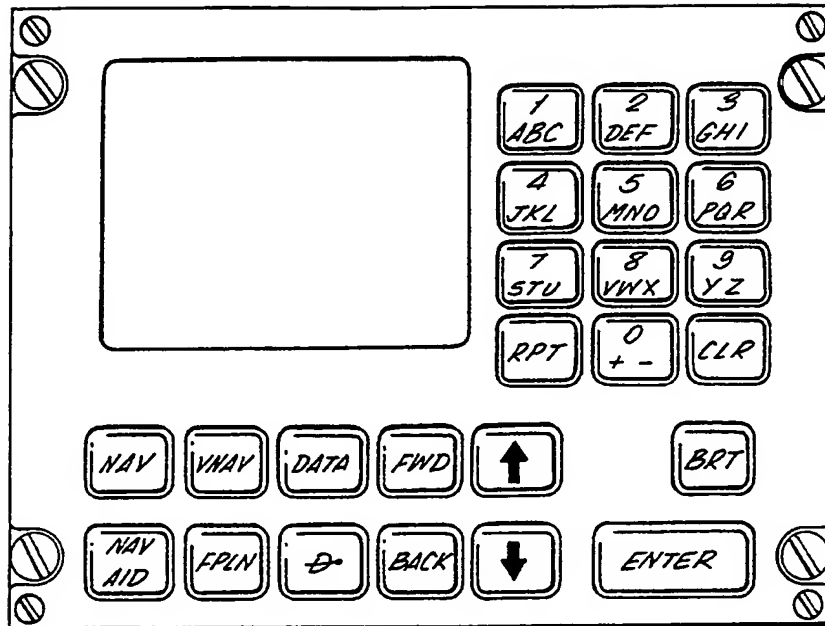
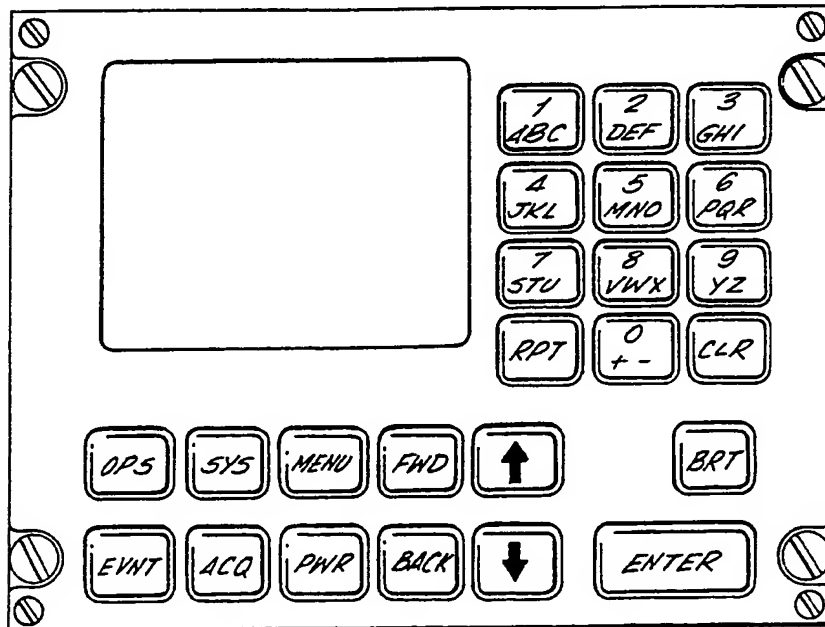
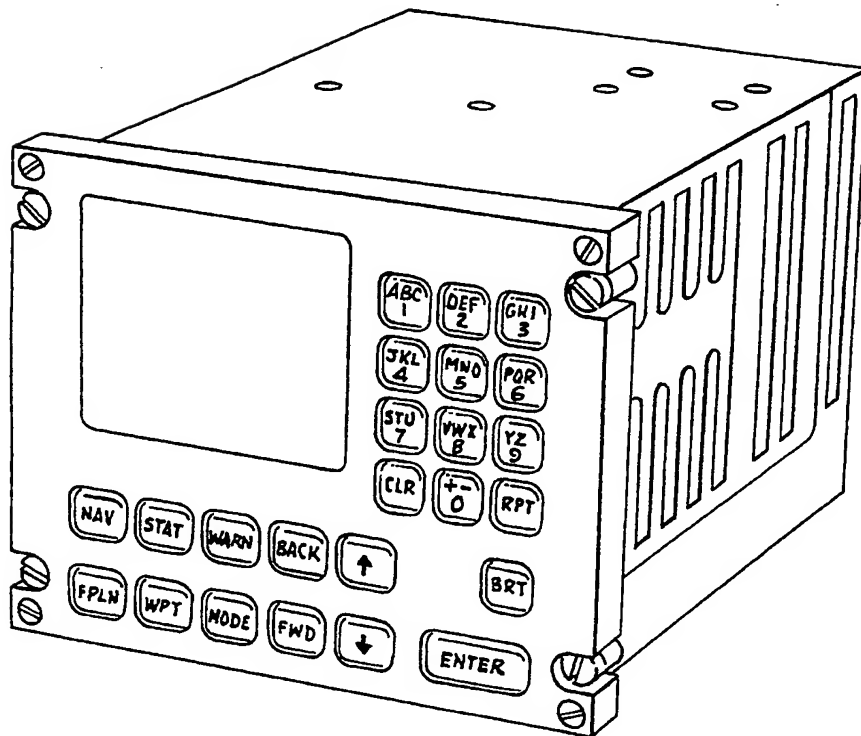


FIG. 10.



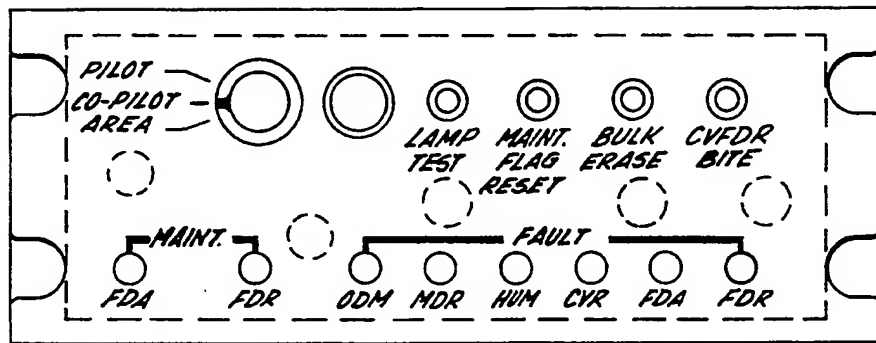
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FIG. 11.
THE CDU.



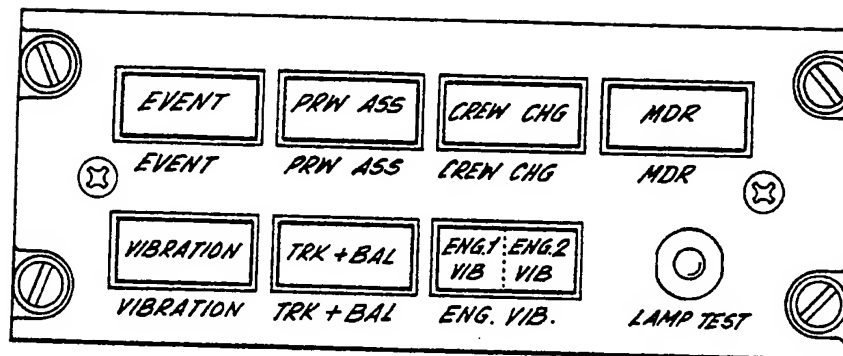
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FIG. 12.
THE I.M.P. PANEL



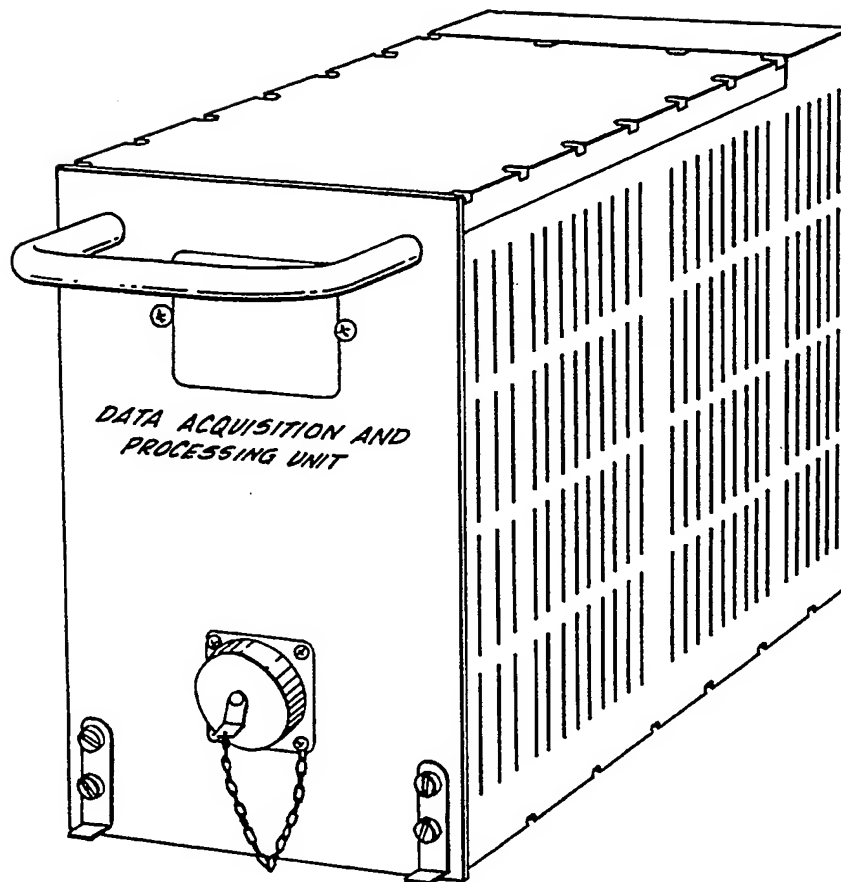
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FIG. 13.
THE P.I.P. PANEL



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FIG. 14.
THE D.A.P.U.



AIRCRAFT HEALTH AND USAGE MONITORING SYSTEM

5 This invention relates to an aircraft health and
usage monitoring system. The term "health" as used
throughout this specification is intended to mean the
condition of a part or system of the aircraft to
perform the function required of it. It is known to
provide flight data recorders (FDR) and cockpit voice
10 recorders (CVR) in aircraft to record flight data and
cockpit crew voices respectively when an aircraft is
in use for subsequent analysis in the event of an
accident. The object of this invention is to provide
a system for monitoring the health and usage of
15 certain important aspects of an aircraft component and
system when in use to assist in the maintenance of an
aircraft and also to provide relevant data in the
event of a failure of a component or system.

20 Thus the present invention provides an aircraft
health and usage monitoring system comprising a
computer system for processing data relating to both
flight profiles and selected indicators of health and
usage of an aircraft, means to monitor the flight
25 profile and the selected indicators and to supply
corresponding data to the computer system, the
computer system having predetermined thresholds
therein in respect of the selected indicators and
being arranged to record the duration and extent by
30 which any threshold is exceeded in use of the aircraft.

By way of example, in the case of a helicopter,
the selected indicators may include the main rotor
track and balance, tail rotor balance, air frame
35 vibration, main gearbox vibration, intermediate
gearbox vibration, tail gearbox vibration, accessory

gearbox vibration, engine vibration, gearbox oil debris and engine oil debris. More specifically, means may be provided for monitoring and supplying data to the computer system for total engine running times, time spent by engines operating in selected operating bands, time spent by rotor systems including main, intermediate, tail and accessory gearboxes in selected operating conditions and total running time for rotor heads and transmission systems.

10

The indicators may include means for determining stress on one or more components of the aircraft engine(s)/transmission(s)/air frame and the computer system may include means for calculating low cycle fatigue (LCF) from the stress information obtained in relation to those components and for storing the resulting information for subsequent processing.

The computer system may have output means for writing data accumulated therein from the monitoring means in the course of use of the aircraft to a recording medium for use and analysis by a separate ground based computer system to enable the aircraft health and usage to be monitored.

25

To enhance flight safety and meet FDR mandatory recording requirements for aircraft, the health and usage monitoring system may be combined with cockpit voice and flight data recorders.

30

The following is a description of a specific embodiment of the invention, reference being made to the accompanying drawings in which:

35

Figure 1 is a diagrammatic illustration of an integrated flight recording health and usage

monitoring system (HUMS) for an aircraft; and

Figures 2 to 14 illustrate a further embodiment of the invention.

5

The purpose of the system is to obtain data from various aircraft sensors that will enable the operator to monitor the health of various components of the aircraft establish accurate usage cycles during the aircraft flight profile and to provide aircraft flight data information for the Accident Investigators in the event of an incident occurring on the aircraft.

10

The system of Figure 1 comprises a Data Acquisition Processing Unit, (DAPU) as illustrated in Figure 14, a Cockpit Display Unit (CDU) as illustrated in Figure 11, a Digital Flight Data Recorder (DFDR), a Maintenance Recorder, a Ground Base Station and/or a carry on board Diagnostics Computer.

20

The system acquires data, as specified by the CAA, or FAA from the various aircraft sensors which are fed into the DAPU. Examples of such data are listed in the Data Schedule at the end of this description.

25

The FDR sub system is segregated within the DAPU from the HUM sub system to minimise the risk and consequences of common mode failures. (Normal cerification procedures apply to the FDR and CVR parts of the system).

30

Upon initial introduction of the HUM facilities provided by this combined system, there is no change to the maintenance procedures used to ensure the safety of the aircraft. As data is obtained and

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confidence in the system established, certain maintenance credits will be developed with the Approval Authorities. All of the airborne software is designed, built and tested to RTCA DO-178A LEVEL II certification procedures.

The signals are processed within the DAPU into four basic categories, Flight Data Acquisition, Exceedances, Health Monitoring and Usage Parameters. The DAPU will interface the Digital Flight Data Recorder (DFDR), a Quick Access Recorder (QAR), a Maintenance Recorder, a Diagnostics Computer and Cockpit Mounted Control Display Unit. The Cockpit Voice signals may be recorded directly onto the DFDR or onto a dedicated Cockpit Voice Recorder.

In normal operations the DFDR data is only be checked during routine maintenance (normally every 12 months).

The system is designed on a modular basis, so that less extensive systems can be fitted into smaller aircraft. A complete system, such as would be fitted to the larger aircraft as shown in attachment 2 would include:-

(i) COCKPIT VOICE RECORDER (CVR)

Cockpit Voice Recording with separate tracks for Pilots, Co-pilots and Area Microphone Signals on the Combined Accident Data Recorder.

(ii) DIGITAL FLIGHT DATA RECORDER (DFDR)

Flight Data Recording on the Combined Accident Data Recorder with a parameter list which meets

1

transferred to the Maintenance Recorder
detailing:- the Exceedance Parameter, Duration
of Exceedance, Maximum Value of Exceedance, time
into flight at the start of Exceedance, and a
5 copy of the FDR data stream extending throughout
the period of the exceedance and for a few
seconds before and after. An Exceedance flag
will also be identified on the FDR data stream
to the DFDR. An Exceedance Summary will also be
10 available on the Cockpit Display Unit (CDU), for
use by aircrew or maintenance staff.

(vii) LOW CYCLE FATIGUE MONITORING

15 The DAPU will provide for the Low Cycle Fatigue
(LCF) calculations on two engines. The
calculations for up to four components on each
engine will be calculated by extracting selected
flight parameters for each engine from the FDR
20 data stream. The calculated LCF for each
component is added to the cumulative count for
that component and also stored as its per flight
count. The cumulative and per flight LCFs for
each component are maintained in non volatile
25 store. The LCF report for each component is
transferred to the maintenance recorder after
engine shutdown, together with a GMT Time and
Data stamp.

30 (viii) LIFE USAGE MONITORING

The DAPU provides Life Usage reports for the two
engines and transmission systems comprising of:-
1. Total running time, 2. Time spent by each
35 engine above certain speed or torque thresholds,
3. Engine starts, 4. Life Usage reports are

also be provided for up to four transmission systems (i.e. Rotors and gearboxes).

(ix) ENGINE PERFORMANCE MONITORING

5

After pilot initiation the DAPU enables the power assurance to be calculated for each engine by extracting the selected flight parameter for each engine from the FDR data stream. The power
10 assurance calculation for each engine is transferred to the Maintenance Recorder and also to the non volatile store for display on the Cockpit Display Unit (CDU) if installed.

15

(x) MAIN AND TAIL ROTOR TRACK AND BALANCE MONITORING

During certain flight conditions the pilot or the system can activate measurements of the main
20 and tail rotor out of balance vibration, and measurements of the main rotor blade track and lag are also obtained. The DAPU provides a Track and Balance Report comprising of:-
1. Main Rotor Track Summary, 2. Main Rotor
25 Balance Summary, 3. Tail Rotor Balance Summary, 4. FDR frames Parameters prior to and after the event. 5. GMT Time and Data stamp which is transferred to the Maintenance Recorder.

30

(xi) AIRFRAME VIBRATION MONITORING

At an appropriate flight condition, the DAPU automatically initiates acquisition of data from the airframe mounted accelerometers and the
35 rotor track sensor. The DAPU airframe vibration report is transferred to the Maintenance

Recorder together with a DMT Time, Data stamp and the associated frames of the FDR data stream.

(xii) GEARBOX VIBRATION MONITORING

5 The DAPU automatically or by Pilot activated switch initiates acquisition of both raw and synchronously sampled and averaged data from accelerometers mounted on the main intermediate and tail gearbox systems. The signals are formed into a gearbox vibration report, together with frames from the associated FDR data, GMT Time and Date stamps and recorded onto the Maintenance Recorder.

15 (xiii) ENGINE VIBRATION MONITORING

The DAPU automatically initiates acquisition of data from accelerometers mounted on the two engines. The DAPU engine vibration reports are transferred to the maintenance recorder together with a GMT Time, Date stamp and the associated frames of FDR data.

25 (xiv) OIL DEBRIS MONITORING

The DAPU automatically initiates acquisition of data from various types of oil sensors installed in the main, intermediate, and tail gearboxes and, if required, both engines.

30 The DAPU Oil Debris reports for all components are transferred to the Maintenance Recorder together with GMT Time, Date stamp and the associated frames of FDR data.

(xv) COCKPIT DISPLAY

5 The system will be capable of driving a full
Cockpit Display Unit (CDU) which will provide
the pilot with information on exceedances power
assurance, alerts etc., together with the
command button required for the acquisition of
data. If required a simple display of push
10 buttons and lights could be fitted which would
enable the pilot to acquire defined data
together with advisory/warning lights.

(xvi) MAINTENANCE RECORDER

15 The Airborne Maintenance Recorder is usually a
rugged three and a half inch removable media
drive which will interface with the DAPU. This
unit has a formatted storage capacity of 1.4Mb.
Alternative forms of removable media recorders
20 can be used if required.

(xvii) GROUND STATION

25 The Ground Station consists of a Personal
Computer based system which will include printer
and network facilities. The basic Ground
Station will be programmed to accommodate
diagnostic suites for all aircraft types that
are fitted with the HUMS system. The function
30 of the Ground Station will be to:- 1) Produce
and Replay disks, 2) Single data entry point
for pilots/engineers, 3) Identify defects prior
to failure of components, 4) Management of
defects and corrective action taken, 5)
35 Indications and remedies for problems found, 6)
Provide technical records and management

information, 7) Maintenance cycle counts, 8) Provide reliability reports, 9) To generate accurate information and measurements on which engineers can carry out diagnosis of
5 rectification action on aircraft systems. The elements of the Ground Station which relate directly to aircraft maintenance will be developed, built and test to RTCA DO178A LEVEL II certification procedures. The Airborne
10 Maintenance Recorder removable media will be transferred to the Ground Station and will provide Technical Log type information with indications of defects and exceedances that have been identified by the I.HUMS system.

15 An action items identified will have to be cleared by a Technical Log entry before the aircraft will be cleared for further flights.

20 (xviii) DIAGNOSTICS COMPUTER

The Computer is used as a front diagnostics line test set to monitor parameters during fault finding and calibration purposes. In addition
25 it also acts as a front line Ground Station for individual aircraft operating away from the main base.

30 SYSTEM OPERATION

The flying schedule may be entered into the ground station computer (or down loaded from another system) as are the current status of components fitted to the aircraft.

35 Before each flight the Captain is provided with

5 a removable media containing the basic details of the flight. This removable media is placed in the Airborne Maintenance Recorder on the aircraft, where it confirms that the removable media has been fitted to the correct aircraft.

10 The aircraft is not be allowed on a further flight until that removable media has been returned to the Ground Station and the aircraft signed off by the Captain and Maintenance Staff. This, in practice, is equivalent to the current Technical Log process.

15 After completion of the flight, the Captain takes the removable media from the Maintenance Recorder and puts it into the Ground Station Computer. The Short-term Analysis Diagnostic Suites are immediately performed and 1st line reports are printed on the screen together where appropriate with a computer print out.
20 Information displayed are exceedances, component defects, oil debris alerts etc., that have been identified by the airborne system. The report cross-references the action required with the relevant section of the Maintenance Manual.
25

30 Rectifying action by the Maintenance Staff can be identified on the Ground Station Computer effectively clearing the Technical Log.

35 The Ground Station maintains a log of all faults found. This may be extended by the entry of manually identified snags. These faults can be be actioned and closed (or deferred) as required.

Various analysis of the maintenance data base

may be performed; for example identify how many servo valves have been changed on one aircraft or how many times gearbox accelerometers have been replaced etc.

5

The raw data may be analysed using prepared suites of functions for trending and graphing results (i.e. Trending the results of Main gearbox vibration analysis together with the associated oil changes, magnetic plug checks, oil analysis etc.)

10

The system will provide off line analysis and management summaries as required.

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FDR Parameter List for Aircraft
(Greater than 2700 Kg)

5	<u>Parameter</u>	<u>Sample Rate (Hz)</u> <u>12-bit Words</u>	<u>Discretes</u>
	Time (GMT)		1
10	Pressure Altitude	1	
	Indicated Airspeed	1	
	Magnetic Heading	1	
	Normal Acceleration	8	
	Pitch attitude	4	
15	Roll attitude	4	
	Radio Key		1
	No. 1 Engine Ng	1	
	No. 1 Engine Nf	1	
	No. 1 Engine Q	2	
20	No. 1 Engine T4	1	
	No. 2 Engine Ng	1	
	No. 2 Engine Nf	1	
	No. 2 Engine Q	2	
	No. 2 Engine T4	1	
25	Main Rotor Speed	2	
	Collective Pitch	2	
	Longitudinal Cyclic	4	
	Lateral Cyclic	4	
	Tail Rotor Pedal	2	
30	Hyd 1 Pressure		1
	Hyd 2 Pressure		1
	Outside Air Temperature	1	
	AFCS engagement Discretes		1
35			

FDR Parameter List for Large Aircraft
(Greater than 5700 Kg)

5		Sample Rate (Hz)	
	<u>Parameter</u>	<u>12-bit Words</u>	<u>Discretes</u>
	Main gearbox oil pressure	1	
10	Main gearbox oil temperature	1	
	Yaw acceleration	4	
	Sling force load	2	
	Longitudinal Acceleration	4	
	Lateral Acceleration	4	
15	Radio Altitude	1	
	Glideslope Deviation No. 1	1	
	Localiser Deviation No. 1	1	
	Glideslope Deviation No. 2	1	
	Localiser Deviation No. 2	1	
20	Marker Beam Passage (3 off)		1
	Warnings		1
	NAV Frequency selection		
	DME distance	1	
	Latitude	1	
25	Longitude	1	
	Nav computed groundspeed		
	Nav computed drift angle		
	Landing gear		1
30			
35			

5 A further example of the integrated Health and Usage
Monitoring system (IHUM) in accordance with the invention
which will now be described with reference to Figures 2 to
10. The system provides for the automatic sensing and
recording of data from a number of strategically
positioned sensors, both on the airframe and the major
mechanical components; flight Data Recorder parameters are
transferred to a combined Cockpit Voice and Flight Data
10 Receorder (CVFDR) whilst the Health and Usage Monitoring
parameters are transferred to a Maintenance Data Recorder
(MDR).

AIRBORNE DIAGNOSTICS

15 The pilot may interrogate the system during flight,
via a Cockpit Display Unit (CDU), and may also enter
additional operational information on the CDU, usage and
exceedance may be viewed.

20 Date is transferred onto a removeable media during
the flight/mission, for subsequent transfer to a
groundstation Personal Computer.

GROUND BASED DIAGNOSTICS

25 Analysis of the data is performed in two stages.
The first stage is completed within one minute and
identifies the aircraft/component usage, together with any
30 exceedances that may have occurred during the flight which
would generate a technical log entry to place the aircraft
unserviceable. The second stage takes approximately 3
minutes to complete during which time a large number of
parameters are closely analysed.

35 From some of the data extracted, changes in the

state of the helicopter and its equipment may be tabulated. These trends, when evaluated, provide a vital aid to preventative maintenance in that equipment which starts to show an increase in normal levels can be removed
5 before irreparable damage occurs.

GLOSSARY OF TERMS

10	A & AEE	- Aeroplane and Armament Experimental Establishment
	AAIB	- Aircraft Accident Investigation Branch
	ABS	- Analogue Digital Converter
	AIDS	- Aircraft Integrated Data System
	ARINC	- Aeronautical Radio Incorporated
15	ATA	- Air Transport Association of America
	ATR	- Air Transport Radio
	BALPA	- British Airline Pilots Association
	BHL	- Bristow Helicopters Limited
	BIT	- Built In Test
20	BITE	- Built In Test Equipment
	CAA	- Civil Aviation Authority (United Kingdom)
	CVR	- Cockpit Voice Recorder
	CDU	- Control and Display Unit
	CVFDR	- Combined Voice and Flight Data Recorder
25	CRT	- Cathode Ray Tube
	CTS	- Clear To Send
	DAPU	- Data Acquisition and Processing Unit
	DAU	- Data Acquisition Unit
	DEG	- Degress
30	DFDR	- Digital Flight Data Recorder
	DITS	- Digital Information Transfer System (ARINC 429)
	DOS	- Disk Operating System
	DTU	- Data Transfer Unit
35	EEPROM	- Electrically Erasable Programmable Read Only Memory

	EGT	- Exhaust Gas Temperature
	EPRM	- Erasable Programmable Read Only Memory
	EUROCAE	- European Organisation for Civil Aircraft Electronics
5	FAA	- Federal Aviation Authority
	FDAU	- Flight Data Acquisition Unit
	FDEP	- Flight Data Entry Panel
	FDR	- Flight Data Recorder
	FPM (fpm)	- Feet Per Minute
10	FSK	- Frequency Shift Keying
	GMT	- Greenwich Mean Time
	GS	- Groundstation
	G/S	- Glide Slope
	IGB	- Intermediate Gear Box
15	IHUMS	- Integrated Health and Usage Monitoring System
	IMP	- IHUMS Maintenance Panel
	LCF	- Low Cycle Fatigue
	LRU	- Line Replaceable Unit
	LSB	- Least Significant Bit
20	LWC	- Liquid Water Content
	LWL	- Left Wing Low
	KN	- Knots
	KIAS	- Knots Indicated Airspeed
	MDR	- Maintenance Data Recorder
25	MGB	- Main Gear Box
	MIL-STD	- Military Standard (USA)
	MMI	- Main Machine Interface
	MPOG	- Minimum Pitch On Ground
	MRG	- Main Rotor Gearbox
30	MSB	- Most Significant Bit
	MS-DOS	- Microsoft - Disk Operating System
	MSLS	- Multi Sector Load Sheet
	Nf	- Free Power Turbine Speed
	Ng	- Gas Generator Speed
35	Nr	- Main Rotor RPM
	Nt	- Tail Rotor Speed

	NVR	- Non Volatile Ram
	NVRAM	- Non Volatile Random Access Memory
	ODM	- Oil Debris Monitoring
	PAV	- Pleassey Avionics
5	PC	- Personal Computer
	PIP	- Pilots IHUMS Panel
	PSD	- Project Specification Document
	Q	- Engine Torque
	QAR	- Quick Access Recorder
10	QDM	- Quantitative Debris Monitor
	RADS	- Rotor Analysis Diagnostic System
	RAM	- Random Access Memory
	RMS	- Root Mean Square
	RNAV	- Area Navigation System
15	RPM (rpm)	- Revolutions Per Minute
	RRPM (rrpm)	- Rotor Revolutions Per Minute
	RTB	- Rotor Track and Balance
	RTCA	- Radio Technical Commission for Aeronautics
	RTS	- Ready To Send
20	RWL	- Righth Wing Low
	RZ	- Return to Zero
	SEC	- Seconds
	SIU	- System Interrogation Unit
	SOAD	- Spectrographic Oil Analysis Programme
25	SSD	- Software Specification Document
	TGB	- Tail Gear Box
	TRG	- Tail Rotor Gearbox
	TTL	- Transistor Transistor Logic
	WHL	- Westland Helicopters Limited
30	w.p.s.	- Words per second
	w.r.t.	- with respect to

5

1. System Description

Reffering firstly to Figure 2, the IHUMS consists of
a number of airborne equipments and some ground
10 equipment. An aircraft certification change to
accommodate changes in maintenance which may be introduced
by IHUMS may be required.

The system is designed to be compatible to all
15 current twin turbine single rotor helicopters. It is not
directly applicable to tandem rotor aircraft, although a
modified computer unit would be able to provide the daul
rotor trackers and larger number of sensor inputs needed
for this aircraft.

20

2. System Elements

A Data Acquisition

The airborne installation is based around a Data
25 Acquisition Processing Unit (DAPU), with an associated
Control and Display Unit (CDU) mounted on the interseat
console. The DAPU is interchangeable between a number of
aircraft types without modification. A considerable
amount of extra instrumentation is required, although
30 wherever possible the existing aircraft instruments are
used. Several versions of the DAPU are available to meet
customers fleet requirements

This unit contains all the conditioning circuitry
35 necessary to sample and accurately monitor a wide range of
different types of electrical inputs for subsequent

recording, measurement or processing. The mandatory data output interfaces to a standard ARINC 573/717 Flight Data Recorder and a standard ARINC Quick Access Recorder (QAR). Selected mandatory data together with raw and partially processed HUM data is also fed to a Maintenance Data Recorder (MDR).

The DAPU uses twin microcomputers with shared memory to simultaneously perform real time monitoring and intermittent health monitoring tasks. One microcomputer analyses DFDR data in real time for exceedances, flight condition identification, LCF computation etc, thereby leaving the second microcomputer free to handle irregular tasks such as interfacing to the CDU or SIU, and controlling the vibration acquisition tasks. Both microcomputers run the ADA multitasking operating system.

A non-volatile memory is incorporated within the DAPU which contains computed results such as LCF counts, exceedances and component operating times. Documentary data such as a/c ident, engine number, gearbox number etc. is also stored. This memory can be downloaded/uploaded by the aircrew via the Maintenance Data Recorder.

Comprehensive BIT facilities to satisfy the new CAA requirements have also been incorporated.

The Data Acquisition and Processing Unit (DAPU) acquires data for both the Digital Flight Data (accident) and Health and Usage (maintenance) Recorders.

B Accident Data Recording

Referring to Figure 3 of the drawings IHUMS adopts a combined voice and data recorder in order to save a very significant amount of weight and space. While this approach is acceptable to the CAA, the design permits any

suitable configuration of crash protected recorders to be used albeit with an operational penalty (i.e. the introduction of separate cockpit voice and flight data recorders).

5

C Maintenance Data Recording

Maintenance systems which gather and store data will generate considerable amounts of information, therefore some form of storage is necessary. The solution to these problems adopted by IHUMS is to use electromagnetic removeable media as illustrated diagrammatically in Figure 4.

10

D Ground Station

Ground based computers receive the data carried from the aircraft by the pilot, and carry out analysis and archiving programs. In order that the system can be used to support single operated aircraft as well as large fleet operations, the ground based computer system is able to run on either a modest portable computer or a multi-processor networked system.

15

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D Exceedance Monitoring

A large number of exceedance conditions will be continuously available using data from the DFDR data stream and limits and thresholds stored in NVR. The limits and thresholds can be updated, monitored to allow for changes in component modification state. Whenever any one of the monitors detects an exceedance, a time history of the event will be available for ground analysis. This record shall last from a time 4 seconds before the start of the event to a time either 20 seconds later or 4 seconds after the end of the event, whichever is the sooner.

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The exceedances are identified using bit mapped

words passed into the DFDR data stream and a log record is built identifying the type of exceedance, the duration of that exceedance, the maximum value obtained by the critical parameter and time of the start of the exceedance. For some exceedances it is necessary to establish a cumulative count of the time spent in that condition, and so the DAPU stores a cumulative count in non-volatile form for all monitored exceedances.

NOTE: Some exceedance criteria are subsets of others, for example Ng greater than 105% can only occur while Ng is greater than 100%. In cases such as this, one time history will be created, relating to the exceedance Ng greater than 100%, yet two log records will be created to identify the time spent in exceedance of each threshold level separately.

E Low Cycle Fatigue

Low Cycle Fatigue (LCF) indices are calculated for up to four components on each engine. The algorithms used are obtained from the Aircraft Operating Manual or Engine Manufacturers manual. The incremental and cumulative LCF count are held in NVR, upload along with other component lives and cycle counts. To support accurate LCF calculations the DAPU accommodates Ng sampling at 4 Hz and Nf sampling at 2 Hz.

F Engine Performance Monitoring

The DAPU implements the engine power assurance algorithms from the aircraft manufacturers flight manual. Wherever possible this will permit preflight assurance checking.

It is often necessary for the pilot to ensure that the engines are set in a suitable operating condition

before gathering data for power assurance purposes, therefore this process will always be pilot initiated. On some aircraft a single initiation will relate to both engines, whereas for other aircraft types the engines are checked separately and so two initiations are required. In either case, whenever the pilot initiates engine performance monitoring, a frame of DFDR data shall be stored onto the maintenance recorder.

The DAPU will compute the performance indices using algorithms pertinent to that aircraft type.

The result shall be computed in not more than 30 seconds and preferably in less than 10 seconds. A data file containing a DFDR data frame will still be stored to allow the ground computer to obtain power assurance data for trending and any other analysis.

G Trending Data

This facility allows the pilot to enter data into the IHUM system via the CDU, normally when the aircraft is flying in the cruise. Such data is used for trend monitoring over a number of flights, and includes parameters which are not instrumented by the DAPU such as hydraulics and engine oil temperatures and pressures.

When the pilot has entered this data, a frame of DFDR data is added to identify the flight condition and to allow all the instrumented parameters to be trended over consistent flight conditions.

H Track and Balance

Track and balance data capture falls into three categories. Firstly, data is automatically acquired on routine flights (in a number of flight conditions on each

flight) from which the health of the main and tail rotor systems are monitored using analysis programs running on the ground computer. Secondly, the pilot can initiate data capture to identify particular problems on the aircraft when necessary, and thirdly it is possible to monitor the airframe vibration and main rotor track signals using the SIU during maintenance test flights.

(1) Routine Acquisition for On Board Processing

On every flight, a measurement of the main and tail rotor out of balance vibration and main rotor track is made at a number of positions around the aircraft, and data is recorded automatically during identified flight conditions so that the IHUM groundstation can develop a trend of rotor order vibration magnitude. When the vibration exceeds a threshold level, or when the corrective maintenance action is sufficient to warrant implementation the groundcrew are prompted to carry out a corrective maintenance action. When this has been carried out the aircraft will be returned to service. A complete set of rotor track and balance data is then gathered on the next flight to check that the maintenance action has been applied correctly and to check that the level of vibration has decreased. The two data sets (obtained before and after maintenance) then provide a basis for refinement of the maintenance algorithms.

(a) Main Rotor Track

The system interfaces directly to either an active or a passive rotor track sensor as illustrated in Figure 5. Data from the sensor is used both for acquisition of data for diagnostic purposes (track and balance) and for recording blade position information for the DFDR.

(b) Main Rotor Balance

Up to eight accelerometers are fitted around the

cockpit, cabin and tail to measure the airframe vibration due to main and tail rotor out of balance and aerodynamic forces.

5 (c) Tail Rotor Balance

The tail mounted accelerometer(s) is used to monitor tail rotor out of balance forces, using signal processing as for the main rotor forces except that the processing is synchronous to a tail rotor aximuth marker as illustrated in Figure 6.

(d) Airframe Vibration

Data is obtained from the airframe accelerometers for diagnosis of vibration at other than the first harmonic.

(2) Pilot Initiated Acquisition

The data acquired is the same as for routine acquisition, except that it is annotated as having been required by the pilot.

(3) Maintenance Acquisition

During dedicated maintenance test flights, the SIU can be carried onto the aircraft and connected into the IMP port. The maintenance engineer is then able to initiate any of the DAPU acquisition modes, with the data being fed directly back to the SIU.

I Gearbox Vibration

Gearbox vibration data is used to detect gear and/or bearing defects within all of the stages of the helicopter gearboxes including the accessory drives. Data capture may be initiated by the pilot but is normally be acquired automatically for on board processing to monitor airborne capability. The downloaded data is analysed using special-to-type programs on the ground to yield

information on the condition of each element of each gearbox in the aircraft. Automatic recognition of alert levels in the groundstation is essential because of the large number of parameters present.

5

J Engine Vibration

Two types of engine vibration monitoring are supported, namely in-flight and ground based monitoring.

10

(1) In-Flight Monitoring

Due to the rapid propagation rate of certain gas turbine failure modes, limited continuous monitoring is performed by the DAPU as illustrated in Figure 7.

15

The basic sequence of operations runs as a continuously repeating loop having lower priority than any pilot, maintenance crew or automatically initiated task. The loop monitors each of the four engine shaft in sequence before repeating the cycle. While no other operations are in progress the loop cycle time is approximately one minute. This time is extended if other tasks which use the same signal paths are in progress.

20

(2) Routine Monitoring

25

Routine engine vibration analysis is based upon recording both the raw vibration signals from the engine mounted accelerometers and the engine speed parameters fed to the FDAU. On the ground, spectral analysis techniques are used to compute a vibration spectrum and the speeds of the rotating components are incorporated to identify any unwanted peaks which occur.

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K Ancillary Equipment Vibration

A single piece of ancillary equipment such as an oil cooler fan can be monitored using an accelerometer and, if necessary, a dedicated magnetic pickup for

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synchronisation. Synchronous or asynchronous sampling will be available and the data acquisition processes described in Appendix B for gearbox vibration will be used.

5 L Oil Debris Monitoring

On-line oil debris monitoring will be included when suitable sensors become available.

10 M Oil Sampling

IHUM as a system supports oil sampling by prompting maintenance personnel to take oil samples at the required periodicity, and by accepting oil analysis results into the IHUM groundstation database. It will be possible to recall and plot concentrated oil debris records over the life of any gearbox or engine. Data relating to component changes and oil changes will be presented alongside oil debris results.

20 N Configuration Control

The flight data acquisition section of the DAPU is pin programmable between eight aircraft types for IHUMS. However, there is an additional requirement for certain categories of data, such as exceedance limits, to be modified in the field. This type of data is held in non-volatile storage thereby enabling the system to monitor and record any exceedances correctly. To control parameter changes in non-volatile storage, configuration control codes in that storage are changed whenever the controlling parameters are modified. A test of the configuration control is carried out on every start up by comparing the expected control codes included in the MDR removable media uploaded data with those already in NVR. This method allows a DAPU to be switched between aircraft types and to monitor exceedances and record the data that the preset parameters for that aircraft type dictates.

O Operational Data Input

5 The pilot is able to initiate IHUMS processes and enter operational data, on the ground and in-flight, which is stored on the MDR for downloading into an operational system.

Component Descriptions

A Data Acquisition and Processing Unit (DAPU)

10 This unit contains all the conditioning circuitry necessart to sample and accurately monitor a wide range of different types of electrical inputs for subsequent recording, measurement or processing. The mandatory data output interfaces to a standard ARINC 573/717 Flight Data
15 Recorder and a standard ARINC Quick Access Recorder (QAR). Selected mandatory data together with raw and partially processed HUM date is also fed to a Maintenance Data Recorder (MDR).

20 The DAPU uses twin microcomputers with shared memory to simultaneously perform real time monitoring and intermittent health monitoring tasks. One microcomputer analyses DFDR data in real time for exceedances, flight condition identification, LCF computation etc, thereby
25 leaving the second microcomputer free to handle irregular tasks such as interfacing to the CDU or SIU, and controlling the vibration acquisition tasks. Both microcomputers run the ADA multitasking operating system.

30 A non-volatile memory is incorporated within the DAPU which contains computer results such as LCF counts, exceedances and component operating times. Documentary data such as a/c ident, engine number, gearbox number etc. is also stored. This memory can be downloaded/uploaded by
35 the aircrew via the Maintenance Data Recorder.

Comprehensive BIT facilities to satisfy the new CAA requirements have also been incorporated.

5 The Data Acquisition and Processing Unit (DAPU) acquires data for both the Digital Flight Data (accident) and Health and Usage (maintenance) Recorders.

The functions of the DAPU are as follows:

Usage (Maintenance)

10 (a) It will record and retain in non-volatile memory the Engine Running Time for each engine, the bearboxes and other lifted components.

15 (b) The DAPU will calculate and retain in non-volatile memory Cumulative counts for engine starts, rotor engagement, take-off and landings, perform exceedance monitoring of engine, rotor and transmission parameters. Exceedance recordings include a complete time history from the FDR data stream etc. for post flight analysis and a summary for display on the cockpit CDU.

20 (c) Low Cycle Fatigue indices will be calculated for up to four components on each engine.

25 (d) Engine health monitoring will be calculated automatically on pilot demand.

Health (Maintenance) On Board Processing

The DAPU provides the following "in flight" diagnostics:-

30 (a) continuously perform exceedance monitoring of engine, rotor and transmission parameters. Exceedance recordings will include a complete time history from the FDR Data Stream etc. for post-flight analysis, and a summary for display on the CDU. Exceedances will be classified to yield outputs suitable for inclusion in the DFDR data stream (36 flags) or for the PIP (2 levels of annunciation).

- (b) monitor the engines for excessive vibration.
 - (c) perform engine exhaust gas monitoring when suitable sensors became available.
 - (d) upon pilot initiation, the system will:-
 - 5 (1) sequentially gather data for:-
 - (a) airframe vibration.
 - (b) vibration of main, intermediate, tail, and where fitted, combiner gearboxes.
 - (c) vibration of ancillary components.
 - 10 (2) sequentially gather data for main rotor track and balance and tail rotor balance.
 - (3) carry out engine performance monitoring when demanded by the pilot.
 - (4) enter trending data.
 - 15 (5) display system status on CDU.
 - (e) If no pilot initiated task is in progress, the SIU may be used to initiate any one of the following types of data acquisition:-
 - 20 (1) airframe vibration.
 - (2) main rotor track and balance.
 - (3) tail rotor balance.
 - (4) vibration of the main, intermediate, tail, accessory and, where fitted, combiner gearboxes.
 - 25 (5) engine vibration.
 - (6) ancillary equipment vibration.
 - (7) oil debris sensor monitoring (when sensors are available)
 - 30 (8) engine exhaust gas monitoring (when sensors are available).
 - (9) DFDR monitoring.
- NOTE: When initiated from the maintenance computer these process output data only to the SIU and not to the maintenance recorder.
- 35

(f) If neither pilot or maintenance engineer initiated tasks are in progress, the DAPU will detect certain specified flight conditions and at the correct condition automatically initiate the appropriate process from the following:-

- (1) recording FDR data to the maintenance recorder.
- (2) airframe vibration, vibration of the main, intermediate, tail, accessory and, where fitted, combined gearboxes, engine vibration and ancillary equipment vibration.
- (3) main rotor track and balance and tail rotor balance.

NOTE: Any automatically initiated data gathering process will be nullified by a manually initiated process.

(4) Self Test

The DAPU performs continuous self-testing.

Control and Display

Types of pilot display utilised are:-

- (1) Pilots IHUMS Panel (PIP)
- (a) PIP Description

Referring to Figure 8 of the drawings, the PIP is a small panel of ARINC rail width, with all of the controls and indications necessary to use the IHUM system. However, it is not able to perform the functions which require a test output and so exceedance display, power assurance results display, operations data entry etc. are not catered for in systems fitted with this panel.

PIP units are to be installed on small aircrafts such as Bell 212, S76 etc. where space is limited,

associated with an IMP unit the panel of which is illustrated in Figure 12.

5 PIP panel is provided with background lighting to illuminated legends. Power is 28V dimmed.

(b) PIP Buttons

10 The PIP illustrated in Figure 13 has six press button momentary action switches. Of these, five are associated with the IHUM DAPU functions, and carry legends that are illuminated while the function is active.

These switches are inscribed:-

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TRK/BAL	Green	VIBRATION:	Green
EVENT:	Green	PWR ASS:	Green
CREW CHG:	Amber		

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The other switch is a basic unlit push button which enables to perform a lamp test and is marked "LAMP-TEST".

(c) PIP Indicators

25 PIP panel is provided with two dual lamp sunlight readable square indicators to reflect Engine 1 and 2 vibration warnings and MDR warning.

These warning captions are marked - ENG VIB
- MDR

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Illuminated switches bulbs and the ENG VIB and MDR indicators are powered by the 28V Day/Night.

DATA SUMMARY

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POWER (LAMPS) 28V DC TO DO-160B

POWER (LOGICS) 5V DC (DERIVED FROM 15V DC)
POWER OPERATING 15V DC

ENVIRONMENTAL: TO RTCA DO-160B
5 TEMPERATURE: CATEGORY A1
ALTITUDE/HUMIDITY: OPERATING 15 DEGREES C TO 70 DEGREES C
VIBRATION/MACH SHOCK: CATEGORY J/Y
EMC COMPATIBILITY: CATEGORY A

- 10 (d) Use of DAPU-Related Functions
(1) Event

Pressing the EVENT button will activate the pilot event function, and for a period of 5 seconds from that moment the caption will be illuminated. This function
15 shall operate at all times, including a crew change.

(2) Vibration Acquire

Pressing the VIBRATION button will initiate a complete set of vibration acquisitions. During this
20 period the caption will be illuminated. This function may only be selected if the TRK/BAL and CREW CHG captions are extinguished.

(3) Acquire Rotor Track and Balance Data

25 When the pilot presses the TRK/BAL button, the IHUM DAPU will start to acquire the data as defined by the vibration acquisition table for pilot initiated track and balance. While the acquisition is in progress, the caption shall be illuminated. This function may only be
30 selected if the VIBRATION and CREW CHG captions are extinguished.

(4) Power Assurance

35 Pressing the PWR ASS button will initiate a power assurance data acquisition, and the caption will be illuminated for a period of 5 seconds. This function may

only be selected if the CREW CHG caption is extinguished.

(5) Crew Change

5 This option is used to initiate the rotors running crew change option. If the pilot presses this in flight, nothing will happen and the caption will not illuminate. Similarly, the option shall not operate when any other caption (TRK/BAL, VIBRATION, EVENT or PWR ASS) is lit.

10 If the aircraft is on the ground and no caption is lit when this option is selected, the caption will illuminate and the DAPU will write the appropriate data files to the MDR. The pilot may extract the removable
15 media from the MDR when the "Busy" lamp located inside the door of the MDR goes out.

 When a removable media for the next crew has been prepared by the groundstation and inserted into the MDR, a
20 second press of the crew CHG button will instruct the DAPU to read the required data files from the MDR. The caption will extinguish on the second press.

(2) Cockpit Display Unit (CDU)

25 The CDU illustrated in Figures 9 and 11 is shared with the RNAV navigation system, having both ARINC 429 and RS422 interfaces. In some cases the CDU will be dedicated only to IHUMS, although both interfaces will still be fitted.

30 This unit acts as the centralised acquisition and entry panel for all forms of data. The CDU is the Racal RNAV2 having a monochrome CRT display. The unit will have dual capability being able to act as both an RNAV2
35 navigational computer, and a HUM CDU. This gives the advantage that on all aircraft fitted with an RNAV2

installation, a single display will be available, thus further reducing the weight and size of two separate units.

5 (a) Control of Operating Mode

Dedicated IHUMS only CDU.

10 In this case the CDU shall power up in IHUM Mode, and will stay in that mode in all cases.

15 (3) Shared RNAV-2/IHUM CDU

15 In this application illustrated in Figure 10 the CDU will power up in RNAV-2 mode, and may be switched back and forth between RNAV-2 and IHUM modes under pilot control as defined in this paragraph.

20 To obtain access to the IHUMS system from RNAV-2, the "up" and "down" keys will be pressed together. On change of mode, the CDU will transmit a "DATA" key code to cause the IHUM system to write the main IHUM menu screen.

25 To obtain access to the RNAV system the pilot may (a) press the "up" and "down" keys together, in which case the system will display the last screen used before leaving RNAV-2, or (b) press one of the specific keys (NAV, VNAV, NAV AID, Flight Plan or Go Direct) to bring up the associated screen directly, or (c) press DATA, when in IHUM Mode with an RNAV warning caption shown in the top right of the screen, in which case the CDU will change to RNAV mode and bring up the warns page directly.

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CLAIMS

1. An aircraft health and usage monitoring system comprising a computer system for processing data relating to both flight profiles and selected indicators of health and usage of an aircraft, means to monitor the flight profile and the selected indicators and to supply corresponding data to the computer system, the computer system having predetermined thresholds therein in respect of the selected indicators and being arranged to record the duration and extent by which any threshold is exceeded in use of the aircraft, the indicators of the health and usage of the aircraft being selected from the following: engine health, transmission health, airframe health, aircraft systems health.

2. An aircraft monitoring system as claimed in Claim 1, wherein the computer system includes means for downloading information recorded in the computer system relating to the aircraft health and usage for on board processing or subsequent analysis.

3. An aircraft monitoring system as claimed in Claim 2, wherein the computer system has output means for writing data accumulated in the computer system from the monitoring means in the course of use of the aircraft to a recording medium for on board processing or use and analysis by a separate ground based computer system to enable the aircraft health and usage to be monitored.

4. An aircraft monitoring system as claimed in any of Claims 1 to 3, including display means for displaying to the aircrew when one or more of the selected indicators is exceeded.

5. An aircraft monitoring system as claimed
in any of the preceding claims and in the case where
the aircraft is a helicopter wherein the indicators
are selected from the following: main rotor track
and balance; tail rotor balance; airframe vibration;
main gearbox vibration; intermediate gearbox
vibration, tail gearbox vibration; accessory gearbox
vibration; engine vibration; gearbox oil debris and
engine oil debris.

6. An aircraft monitoring system as claimed
in Claim 4, wherein means are provided for monitoring
and supplying data to the computer system for total
engine running times, time spent by engines operating
in selected operating bands; time spent by rotor
systems including main, intermediate, tail and
accessory gearboxes in selected operating condition
and total running time for rotor heads and
transmission systems.

7. An aircraft monitoring system as claimed
in Claim 5 or Claim 6, wherein the indicators include
means for determining stress on one or more
components of the aircraft engine(s)/transmission(s)/
air frame and the computer system includes means for
calculating low cycle fatigue (LCF) from the stress
information obtained in relation to those components
and for storing the resulting information for
subsequent processing.

8. An aircraft system as claimed in any of
the preceding claims wherein means are provided for
supplying information relating to engine performance
to the computer system and the computer system
includes means for calculating the engine performance

and storing the resulting information for subsequent processing.

5 9. An aircraft monitoring system as claimed
in any of the preceding claims wherein a crash
protected recorder is provided which is coupled to
the computer system to receive selected flight data
and health information therefrom.

10 10. An aircraft monitoring system as claimed
in any of the preceding claims, wherein a cockpit
voice recorder is included in the system.

15 11. An aircraft monitoring system
substantially as described, with reference to and as
illustrated in Figure 1 of the accompanying drawing.

20 12. An aircraft monitoring system
substantially as described, with reference to and as
illustrated in Figures 2 to 14 of the accompanying
drawings.

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